Joint CCA, ISIC and CACSD, 2004

Program at a Glance Wednesday Thursday Friday Saturday Author Index Keyword Index

Last updated on March 10, 2005. This conference program is tentative and subject to change

Program at a Glance

Plenary or special session Invited session Re

2004 CCA/ISIC/CACSD Technical Program Wednesday September 1, 2004

Wednesday Thursday Friday Saturday Top

and Tutorials Workshop	09:00-17:30 Workshop Room WeDWS <u>Pre-Conference Workshops and Tutorials</u>
Room	

2004 CCA/ISIC/CACSD Technical Program Thursday September 2, 2004

Wednesday Thursday Friday Saturday Top

Track 1 CCA Room 1	08:40- 09:40 Plenary Events Room ThDPL	10:00-12:00 Room 1 ThA01 <u>Aerospace and</u> <u>Vehicle</u> <u>Systems</u>	13:20-15:20 Room 1 ThM01 <u>Aerospace</u> <u>Applications</u>	15:40-17:40 Room 1 ThP01 <u>Control</u> <u>Applications in</u> <u>Aerospace</u> <u>Engineering</u>	17:50- 18:50 Plenary Events Room ThEES
Track 2 CCA Room 2		10:00-12:00 Room 2 ThA02 <u>Communication</u> <u>and</u> <u>Manufacuturing</u> <u>Systems</u>	13:20-15:20 Room 2 ThM02 <u>Real-Time</u> <u>Networked</u> <u>Control Systems</u>	15:40-17:40 Room 2 ThP02 <u>Control</u> <u>Techniques Using</u> <u>Networks</u>	
Track 3 CCA Room 3		10:00-12:00 Room 3 ThA03 <u>Electromagnetic</u> <u>Mechanical</u> <u>Systems</u>	13:20-15:20 Room 3 ThM03 <u>Motor Systems</u>	15:40-17:40 Room 3 ThP03 <u>Applications of</u> Force and Visual Feedback Control to Advanced <u>Mechatronic</u> Systems	
Track 4 CCA Room 4		10:00-12:00 Room 4 ThA04 <u>Control</u> <u>Applications 1:</u> <u>Motion Control</u>	13:20-15:20 Room 4 ThM04 <u>Robot</u> <u>Manipulator</u> <u>Control</u>	15:40-17:40 Room 4 ThP04 <u>Control of Disk</u> <u>Drive Storage</u> <u>System</u>	
Track 5 CCA Room 5		10:00-12:00 Room 5 ThA05 <i>Advanced</i>	13:20-15:20 Room 5 ThM05 Automotive	15:40-17:40 Room 5 ThP05 <i>Bio-Svstems</i>	

	Control Applications	Applications	
Track 6 CCA Room 6	10:00-12:00 Room 6 ThA06 <i>Fuzzy Control</i>	13:20-15:20 Room 6 ThM06 <u>Learning Control</u>	15:40-17:40 Room 6 ThP06 <u>Neural Networks</u> <u>and Fuzzy</u> <u>Systems</u>
Track 7 ISIC Room 7	10:00-12:00 Room 7 ThA07 <u>New Techniques</u> for Intelligent <u>Control</u>	13:20-15:20 Room 7 ThM07 <u>Embedded</u> <u>Intelligent</u> <u>Control and</u> <u>Applications</u>	15:40-17:40 Room 7 ThP07 <u>Modelling and</u> <u>Control of</u> <u>Probability</u> <u>Density</u> <u>Functions</u>
Track 8 ISIC Room 8	10:00-12:00 Room 8 ThA08 <u>Hybrid</u> <u>Dynamical</u> <u>Systems</u>	13:20-15:20 Room 8 ThM08 <u>Randomized</u> <u>Algorithms</u>	15:40-17:40 Room 8 ThP08 <u>Architectures for</u> <u>Autonomy</u>
Track 9 CACSD Room 9	10:00-12:00 Room 9 ThA09 <u>CACSD</u> <u>Toolboxes and</u> <u>Tools</u>	13:20-15:20 Room 9 ThM09 Formal Methods for Supporting the Design of Controllers for Timed and Hybrid Systems	15:40-17:40 Room 9 ThP09 <u>Computer</u> <u>Automated Multi</u> <u>Paradigm</u> <u>Modeling</u>

2004 CCA/ISIC/CACSD Technical Program Friday September 3, 2004 Wednesday Thursday Friday Saturday Top

Track 1 CCA Room 1	08:40- 09:40 Plenary Events Room FrDPL	10:00-12:00 Room 1 FrA01 <u>Linear Control</u> <u>Synthesis and</u> <u>Modeling</u>	13:20-15:20 Room 1 FrM01 <u>Nonlinear Control</u>	15:40-17:40 Room 1 FrP01 <u>Methods for</u> <u>Nonlinear and</u> <u>Robust Control in</u> <u>Specific</u> <u>Applications</u>	17:50- 18:50 Plenary Events Room FrEES
Track 2 CCA Room 2		10:00-12:00 Room 2 FrA02 <u>Hybrid Systems</u>	13:20-15:20 Room 2 FrM02 <u>Hybrid and</u> <u>Constrained</u> <u>System</u> <u>Applications</u>	15:40-17:40 Room 2 FrP02 <u>Mobile Robot</u> <u>Systems</u>	
Track 3 CCA Room 3		10:00-12:00 Room 3 FrA03 Process Control	13:20-15:20 Room 3 FrM03 <u>Advanced</u> <u>Control</u> <u>Technology for</u> <u>Iron and Steel</u> <u>Processes</u>	15:40-17:40 Room 3 FrP03 <u>Advances in</u> <u>Process Control</u> <u>and Monitoring</u>	
Track 4 CCA Room 4		10:00-12:00 Room 4 FrA04 <u>Advanced</u> <u>Motion Control</u>	13:20-15:20 Room 4 FrM04 <u>Examples of</u> <u>Interacting and</u>	15:40-17:40 Room 4 FrP04 <u>Sensor and</u> <u>Control</u>	

		<u>Cooperating</u> <u>Robotic</u> <u>Systems</u>	<u>Applications in</u> <u>Motion Systems</u>
Track 5 CCA Room 5	10:00-12:00 Room 5 FrA05 <u>Control</u> <u>Applications 2:</u> <u>Crane/noise</u> <u>Control</u>	13:20-15:20 Room 5 FrM05 <u>Flexible</u> <u>Structures</u>	15:40-17:40 Room 5 FrP05 <u>Control of Fluid</u> <u>Power Systems</u>
Track 6 CCA Room 6	10:00-12:00 Room 6 FrA06 <u>Neural Networks</u> <u>and Adaptive</u> <u>Control</u>	13:20-15:20 Room 6 FrM06 <u>Learning Control</u> <u>Applications</u>	15:40-17:40 Room 6 FrP06 <u>Robust Control</u>
Track 7 ISIC Room 7	10:00-12:00 Room 7 FrA07 <u>Recent</u> <u>Advances in</u> <u>Intelligent</u> <u>Control</u>	13:20-15:20 Room 7 FrM07 Intelligent and Advanced Control in the Process Industries	15:40-17:40 Room 7 FrP07 <u>Advanced</u> <u>Stabilization and</u> <u>Signal Synthesis</u>
Track 8 ISIC Room 8	10:00-12:00 Room 8 FrA08 <u>Intelligent</u> <u>Control</u> <u>Applications - a</u> <u>Portfolio</u>	13:20-15:20 Room 8 FrM08 <u>Intelligent</u> <u>Control for</u> <u>Robots</u>	15:40-17:40 Room 8 FrP08 <u>Intelligent</u> <u>Adaptive Control</u>
Track 9 CACSD Room 9	10:00-12:00 Room 9 FrA09 <u>Polynomial</u> <u>Design Methods</u>	13:20-15:20 Room 9 FrM09 <u>Scilab/Scicos:</u> <u>An Open Source</u> <u>Environment for</u> <u>CACSD</u>	15:40-17:40 Room 9 FrP09 <u>Interval Tools for</u> <u>Control</u>

2004 CCA/ISIC/CACSD Technical Program Saturday September 4, 2004 Wednesday Thursday Friday Saturday Top

Track 1 CCA Room 1	Events Room	10:00-12:00 Room 1 SaA01 <u>Fault Detection</u> <u>and</u> <u>Accomodation</u>	13:20-15:20 Room 1 SaM01 <u>Manufacturing</u> <u>Systems</u>	15:40-17:40 Room 1 SaP01 <u>Port Automation</u> <u>Technology</u>
Track 2 CCA Room 2	SaDPL	10:00-12:00 Room 2 SaA02 <u>Vehicle Control</u> and Estimation	13:20-15:20 Room 2 SaM02 <u>Automotive</u> <u>Controls and the</u> <u>Advanced</u> <u>Development</u> <u>Environment</u>	15:40-17:40 Room 2 SaP02 <u>Real-Time</u> <u>Prediction and</u> <u>Optimization for</u> <u>Vehicles and</u> <u>Mechanical</u> <u>Systems</u>
Track 3 CCA Room 3		10:00-12:00 Room 3 SaA03 <u>Simulation and</u> <u>Control of</u> <u>Industrial</u> <u>Processes</u>	13:20-15:20 Room 3 SaM03 <u>Control</u> <u>Applications 3:</u> <u>Mechanical/power</u> <u>Systems</u>	15:40-17:40 Room 3 SaP03 <i>Power Systems</i>

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Track 4 CCA Room 4	10:00-12:00 Room 4 SaA04 <u>Adaptive Control</u> and Identification	13:20-15:20 Room 4 SaM04 <i>Filtering and</i> <u>Estimation</u>	15:40-17:40 Room 4 SaP04 <u>Predictive Control</u>
Track 5 CCA Room 5	10:00-12:00 Room 5 SaA05 <u>Sliding Mode</u> <u>Control</u>	13:20-15:20 Room 5 SaM05 New Trends in Fixed/Reduced- Order Robust Controller Synthesis: New Design Algorithms with Advanced CACSD Tools	15:40-17:40 Room 5 SaP05 <i>Robust Motion and</i> <i>Vibration Control of</i> <i>Electromechanical</i> <i>Systems</i>
Track 6 CCA- ISIC Room 6	10:00-12:00 Room 6 SaA06 <u>Adaptive Critic</u> <u>Controls (ISIC)</u>	13:20-15:20 Room 6 SaM06 <u>Intelligent Sensing</u> (ISIC)	15:40-17:40 Room 6 SaP06 <u>Observers (CCA)</u>
Track 7 ISIC Room 7	10:00-12:00 Room 7 SaA07 <u>Fuzzy Systems</u>	13:20-15:20 Room 7 SaM07 <u>Applications and</u> <u>Analyses of</u> <u>Genetic</u> <u>Algorithms</u>	15:40-17:40 Room 7 SaP07 <u>Robustness and</u> <u>Stability in</u> <u>Intelligent Control</u>
Track 8 CACSD Room 8	10:00-12:00 Room 8 SaA08 <u>Computer Tools</u> <u>for Control</u> <u>Education</u>	13:20-15:20 Room 8 SaM08 <u>Tools and</u> <u>Methods for</u> <u>Networked and</u> <u>Real-Time</u> <u>Systems</u>	15:40-17:40 Room 8 SaP08 <u>Controller Design</u> <u>Algorithms</u>
Track 9 CACSD Room 9	10:00-12:00 Room 9 SaA09 <u>LMI-Based</u> <u>Control System</u> <u>Analysis and</u> <u>Synthesis</u>	13:20-15:20 Room 9 SaM09 Software Tools for Semidefinite Programming and Its Applications to Control	15:40-17:40 Room 9 SaP09 <u>Applications of</u> <u>LMIs to Switched</u> <u>and Chaotic</u> <u>Systems</u>